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A Hybrid Real-time Remote Monitoring Framework with NB-WOA algorithm for patients with chronic diseases

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Abstract:

The embracing of the Internet of Things (IoT) and Cloud Computing technologies gives excellent opportunities to develop smart healthcare somiles that have great prediction capabilities. This paper proposes a Hybrid Real-time Ren. vte Monitoring (HRRM) framework, which remote-monitors patients continuously. Th. smart tramework predicts the real health statuses of the patients in real time by using context awa. mess. The proposed HRRM framework innovates a Patient's Local Module (PLM) the au a convergence between IoT sensors and clouds. The HRMM transfers some of the computions to the edge of the network in (PLM) such as converting the low-level data to a high or level of abstraction to speed-up the computations in the cloud portion of the HRMM. The convergence of IoT enables the HRMM to use the enormous cloud power in storing, processing, analyzing big data, building classification models for the category of patients' health tatus. The local portion of the HRMM uses classification models that have been trained in the cloud to predict the health status of the patient locally in the event of internet ir erruption or cloud disconnection to save his life in the disconnection periods. Furthermore, us proper proposes a cloud classification technique that is capable of dealing with big imb landed quataset by minimizing errors especially in the minority class that represents the critical vituations. Finally, a hybrid algorithm of Naïve Bayes (NB) and Whale Optimization Algorith $n (W \gtrsim 4)$ has been proposed to select the minimal set of features that achieve the highest acrue v. The (NB-WOA) works as a safe-failure module that decides when to stop the monitoring usin, HRMM in the case of the failure of influential sensors. Experiments have prov d t at the HRMM is capable of predicting the health status of the patients suffering from bl od pressure disorders accurately. Also, it proved that NB-WOA accelerates the classif cation, "ocess and saves storage space.

Keywords: Smart Healthca. [•] In[•] ernet of Things convergence (IoT); Naïve Bayes (NB); Whale Optimization Algorithm (WOA)[•] Big da⁺a; insbalanced dataset.

1. Introduction

Machine learning has many contributions in the medical field such as Remote Patient's Monitoring (RPM) systems that deliver care to the patient suffering from chronic disease especially elderly patients at his home [1]. RPM is defined as using technology to monitor patients remotely (e.g., at his house) to improve patient's quality of life. It tracks the patient continuously without obstruction to the freedom of his movement to pevent possible complications, and all these services should be provided at reasonable cost [2]. Implantable and wearable biomedical sensors have received much attention over the last two devodes because of the need to collect sensor data that contains physiological signals, patient's a 'ivity during vital signs' measurement, etc. in real time while practicing his daily rout ne 23 IoT exploited the progress in ubiquitous sensing which is qualified by Wireless Se sor Network (WSN) technologies to enable actuators and sensors to interact seamlesslyth the ombient environment and to share the collected information among different platforms IoT h. 3 made a huge leap by enabling various technologies such as near field communica on (NFC), Radio-frequency identification (RFID) and embedded sensor to transform the internet into a fully integrated platform [4,5]. There are many factors that can affect vital igr , v, lues of the patient such as patient's activities (current/last), ambient conditions ('emperatrie, humidity, noise, etc.), patient's habits (sleeping, smoking, alcoholic beverages, tout etc.) and many other factors. Context awareness defines the capability of a system to ather in ormation from the surrounding environment at any time to comprehend it and adap. its b. vior accordingly. Context-aware RPM model uses this technique to comprehend the curre. ' health situation of the patient and provide a personalized health care service accord. 1 [6]. For example, context-aware RPM refers to an emergency case when the patient's heart ra. (HR) increases above normal during sleep while refers to a normal case if the increas in ..., occurs during exercise. This technique can be implemented by aggregating all sensor data . the high-level form in one context state for each period. Machine learning is used to unde. Sun rd the health status of the patient and interpret the fluctuations in the patient's vital signs to provide the proper assistive service [7]. The continuous monitoring of patients using REM mouels is a source of big data generation because the monitoring period may be extended for years with a fast sampling rate may be in milliseconds resulting in the generation of a huge amount of sensor data. Big data is one of the famous terminologies in the current lecade that is used to describe the dataset that fulfills at least one of the characteristics of 4 V's model (Volume- Velocity - Variety - Veracity) according to IBM's formal definition [8]. The refere, the architecture that contains IoT and cloud components collected health data by IoT on the ', cal side [9]. Traditional RPMs depend on a standalone application working on a b nul ald device or local server and always customized for a specific case depending on generic rules [10]. These systems cannot manage big data and cannot be trusted to monitor patier is so ffering from other diseases. Some researchers tried to address these shortcomings by developing, context-aware models to predict the health status of the patient at real-time [11,12]. Furthermole, the recent researches proposed cloud-based frameworks for knowledge extract in f om jig data using clouds for storing and processing patient's context states to predict the pa. an' s health status at the real time. The weak point of these models that they put the pa' ent at risk when the connection with the cloud is lost or internet is interrupted [13,14]. Also, t. ese mo lels ignored the problem of imbalanced datasets that is always present in

- The need for developing context-aware RPM, which uses generic and personalized medical rules to build a customized medical assistant that, comprehends the real health status of the patient to minimize false alarms.
- The urgent need for developing an intelligent hybrid classification model the works locally to save the patient's life in the case of cloud system failure or internet interreption.
- The need to address the shortcomings of the previous models in dealing with imbalanced datasets that result in generating false warnings especially in the emergencies that represent the minority class.
- The need to develop an algorithm that identifies the minimum number of attrioutes required to ensure the continuity of the model's work with highest efficiency and speed.

The rest of this paper is organized as follows: The second section represents related work, which contains Remote Patient Monitor (RPM) models, NB and WOA: The proposed architecture (HRRM) is presented in details in the third Section. The fourth section introduces three case studies for monitoring patients suffering from blood pressure a sorders in real-time, also, the sampling methods that will be used to deal with imbalance date of the Proposed Hybrid Knowledge Discovery Classification Model (HKDM) is presented in the fifth section. The sixth section illustrates the proposed NB-WOA. The evaluation of the proposed classifiers and results are outlined in the seventh Section. Our conclusions and the first work are drawn in the final section.

2. Related work

2.1. The IoT-Cloud Convergence in Smart healthca.

It is expected that many smart medical service, will evolve because of the tremendous development in IoT, cloud, and edge computing durains and the integration among them. This integration helps in developing new medical vs. intive scenarios and new generations of smart medical services and applications. Recently this opic has increased interest in both industry and academia aiming to design and implement. advanced smart healthcare systems. Most of the currently proposed architectures consist of a set of layers for storing, processing, and analyzing medical data.

Abawajy and Hassan [15] pro_{k} sed a sustainable Cloud-Based Pervasive Patient Health Monitoring (PPHM) architectur. The 1 HM architecture contains three layers as follows: Collection Station, Observatic Station, and Data Centre. This architecture has been tested through a case study for real-time monitoring for a patient suffering from congestive heart failure. Chen et al. [16] $r_{O_{k}}$ sed an Edge-Cognitive-Computing-based (ECC-based) smarthealthcare system for monitoring the physical health of users using cognitive computing. Catarinucci et al. [17] $r_{O_{k}}$ sed an IoT aware smart hospital system that collects and monitors patients' parameters using the ultra-low-power hybrid sensing network in real time. Manogaran et al. [18] proposed a new architecture to implement the IoT to process scalable sensor data (big data) for healthcare a_{k} lice ions. In addition, they provide security services using the integration of fog computing with cloud computing. A healthcare service delivery architecture based on fog computing has been private by Andriopoulou et al. [19]. It proposes module between Cloud and IoT derives to chable new types of computing and services. The proposed architecture

consists of three main layers, which are: (i) fog servers for storing, processing, and analyzing data, (ii) fog nodes for data aggregation, and (iii) cloud-based module for data storage. Rahmani [20] proposed a Smart e-Health Gateway using the strategic position at the edge of the network. The concept of Fog Computing in Healthcare IoT systems is exploited by rming a Geodistributed intermediary layer of intelligence between sensor nodes and Cloud. In at 4ition, an IoT-based Early Warning Score (EWS) health monitoring is implemented to a lress a medical case study. Dimosthenis et al. [21] Proposed an integrated Edge-Fog-Civit architecture for Healthcare Internet of Things (EFCHIOT) Infrastructure. The EFCHIOT a hitch re consists of three layers to store medical data, acquire process, and to provide real-time decision-making. The three layers are as follows: the first is the Edge layer that inclues ortable and wearable computational devices, the second is the Fog layer which is reconst, le for gathering and processing data from the Edge nodes, and the third is a cloud inf astructure which is responsible for data storage and analysis of the data uploaded from the combination of Fog and Edge levels. Experimental results have proved that EFCHIoT archite ure provides real-time decisionmaking, fast queries' processing, and less power consumpt. Our proposed architecture has benefited from these ideas by innovating a hybrid architectu. ³ that does the main processing of vital signs in the local portion of the architecture. Moreover, it uses the power of the cloud to store, processes the big imbalanced datasets, and train plass, and models from a huge number of contexts. Additionally, it transfers the classification odd to the cloud portion of the architecture to predict the health status of the patient in the case of internet interruption or cloud disconnection.

2.2. Remote Patient Monitoring (RPM)

RPM has enabled physicians to monitor and obs, we patients remotely using digital technologies that collect health data, ambient condition, acus, ties, etc. in any location, such as a patient's home, and to transmit the collected informa. on electronically to healthcare providers for assessment and taking appropriate action [22,23]. The integration of non-invasive technologies into healthcare management strateg' is by ga hering all possible information from the patient and his ambient environment helps to improve the quality of decision-making [24–26]. RPM is an interdisciplinary field exploiting advancement in many areas such as activity monitoring [27], continuous care [28], personal. ^ad care (29], cloud-based healthcare architectures to achieve a breakthrough in this area [13 14,30]. ^r arlier trials for developing context-aware RPM has some drawbacks, for instance, Line cannot manage big data because they are based on local architecture, each RPM is designed for a specific disease, and they support a limited number of context awareness ser ice: [31,32]. Many researchers struggled to solve the previous shortcomings by developing Context-aware cloud-based models that can extract knowledge from massive data generated non patients' continuous monitoring [33,34]. The most recent researches proposer fle able architectures that facilitates adding or removing contexts easily, and they are suitable for n. nitc ing any patient suffering from any chronic disease [13,14,35]. These architectures w¹ on clouds in their operation, and this raises many inquiries about what will happ n to the monitored patient when the internet connection is interrupted, or failure occurred in the low. system. Furthermore, the problem of imbalanced datasets has been

overlooked, most studies have only focused on accuracy to prove the efficiency of the model, but we believe that this is misleading. The classifier succeeded in predicting patterns that belong to the majority class and failed in the minorities which are more critical in these datasets because they represent the emergency case of the patient [13,14].

2.3. Naïve Bayes

Naive Bayes (NB) is the most popular classifier in the family of probabilidic of assifiers. Naive Bayes classifier uses the probabilistic theory to get the correct classification. (36,37]. NB has proven its effectiveness in many learning scenarios such as medical diagnosis [38,39], text classification [40], sentiment analysis [41], image processing [42,4²] and web mining [44]. Classification using Bayesian network considers the dependency betwork and the correct result [45]. NB is a particular case of the Bayesian algorithm assuming that features are independent of each other [46]. This assumption makes training phase simpler and faster with nearly similar results. NB is working as follows [46]:

Let the training set T has some tuples; each one is represented c_{j} an n-dimensional vector $X=\{x_1, x_2, ..., x_n\}$ and each vector describes n attributes $A_1, A_2, ..., A_n$. Each Sample belongs to one class of m classes: $C_1, C_2, ..., Cm$.

1. For a given a sample X, the classifier will predict that Y belongs to the highest posterior probability of class by recalling Bayes theorem as shown in e luation 1

$$P(C_i | X) = (P(X | C_i) P(C_i)) / P(X)$$
 Posterior - (Like nood × Prior)/Evidence (1)

X is classified to class C_i (class with highest poetician probability), when $P(C_i|X) > P(C_j|X)$, where $1 \le i, j \le m$. In equation 1, the denominator (widence P(X)) is the same for all classes, so only the numerator ($P(X|C_i) P(C_i)$) is the same for all classes. The prior probability of class (C_i) can be calculated as in violation 2:

$$P(C_i) = \sum_{i=1}^{i} I_{i}$$
(2)

, where (S_i) is the number of training samples of class (C_i) and (S) is the total number of training samples. If the prior probability $rm(P(C_i))$ is unknown, the equal probability is assumed for all classes, then $P(C_1) = P(C_2) = ... = P(C_m)$, therefore, the target of equation 1 is transformed into maximization for the term $(P(X | C_i))$ only.

2. The workload for calculating h. lihoor $(P(X | C_i))$ will be very high especially in multidimensional datasets. A simple (na. e) assumption solves this problem by stating that individual attribute values *e* e in teper dent of each other under certain conditions and can be calculated as shown in equation. 3.

$$\Gamma(\mathbf{X} \mid C_i) \approx \prod_{k=1}^n P(x_k \mid C_i) \tag{3}$$

- 3. From given dataset T , 'x₁ | C_i), P (x₂ | C_i),..., P (x_n | C_i), can be calculated from the training set. Where X_k refers to k¹ attribute (A_k) of sample X.
- 4. From equation 1, the . merator $(P(X | C_i) P(C_i))$ will be calculated for each class, so that sample X will be preclicted as C_i member, if and only if, $P(X | C_i) P(C_i)$ is the maximum.

2.4. Whale Optimization Algorithm (WOA)

WOA is a na ure-ins₁ ired meta-heuristic algorithm, which is used to solve optimization problems by min. \dot{c} kin, the motion of the whale when hunting the prey.

2.4.1. Whale in nature

Whales are giant predators, which considered as the biggest mammals in the world reaching a length of 30 meters and weight around 180 tons. There are eight primary species of this giant creature such humpback, finback, blue, killer, Minke, sperm, Sei, and southern right. Whales are brilliant animals, and they are emotionally at the same time because they have shand cells in their brains similar to those called spindle cells in human. These cells in responsible for emotions judgment, social behaviors as in humans and this is the cause of the whale smartness [47]. Hence, a whale can socialize more than other animals and live in group. they can learn, think, judge, communicate and become emotional better than other animals. Yumpback whale is one of the biggest baleen whales, and his favorite preys are krill and s nat fish nerds [48,49]. It has a unique hunting technique called bubble-net feeding method. They have the victim, which is close to the surface by creating bubbles along a '9'-shaped path. According to the most recent studies, Humpback whales adopt two maneuvers techniques associated with bubbles called 'upward-spirals' and 'double loops.' In the first maneuver, the 'umpbrick whales dive in the water around 12 meters down, then start to make a wave of b bles ... a spiral shape encircling the prey. Finally, the whale swims fast toward the surface () he are prey as shown in Fig 1. The second maneuver includes three different stages: coral loop, lo' tail, and capture loop [48]. More details about the whales' behaviors can be found in [48-29].



Fig 1. Bubble-net fe, mg inthe vior of humpback whales

2.4.2. The Mathematical Mimicking model

The unique actions of a humpback y hale in yearching for the prey, encircling the prey and spiral bubble-net feeding maneuver, are man. mat cally modeled as follows:

Encircling prey

Since the target from the movement of the Humpback whales is how to recognize the location of prey to encompass it. WO'. Sumes that the position of the whales are $W_i \forall i = 1, 2, ..., M$, where M is the number of whales thich is initialised randomly in the search space to search for the position of the optimula solution which is unknown. The best location (resolution) is considered as the position of the target prey or close to the optimum position. After the best search agent is defined, the ther search agents will hence try to update their positions towards the best solution or position as in equations 4 and 5

$$\vec{D} = |\vec{C} \cdot \vec{W}^*(t) - \vec{W}(t)|$$

$$\vec{W}(t+1) = \vec{W}^*(t) - \vec{A}.\vec{D}$$
(5)

Where \vec{A} and \vec{C} are coeccient vectors, which are calculated as in Equations 6 and 7 for (t) that represents the current iteration, \vec{W} is the position vector, $\vec{W^*}$ vector represents the e_{1} sition vector of the best solution until now. $\vec{W^*}$ The vector should be updated in each iteration if unere is a better solution.

$$\vec{A} = 2\vec{a}.\vec{r} - \vec{a}$$

$$\vec{C} = 2.\vec{r}$$
(6)
(7)

Where \vec{a} is linearly decreased from 2 to 0 throughout iterations in e_{X_1} tation and exploration phases and \vec{r} is a random vector in [0, 1]. For two-dimensional search s_F are as in **Fig 2**, the position of the candidate W_i that is located at (X, Y) can be updated according to the position of the best candidate (X^*, Y^*) . The values of \vec{A} and \vec{C} vectors con $2^{1-t'}$ are new position of W_i . Accordingly, any position in the search space can be reached by ψ_i^{-1} ating the current position in the neighbourhood of the current best candidate to simulate $\frac{1}{2}$, met od of encircling the prey. This 2-d concept can be extended to n-dimensional search s_F are. The bubble-net feeding behaviour has two phases called exploitation and exploration phases [50,51].

Exploitation phase

In this phase, whales adopt two mechanisms to chase the prey, which can be explained in mathematics as follows:

A. Shrinking encircling mechanism

Decreasing the value of \vec{a} in Equation (6) v⁻¹l control the shrinking mechanism, and then the positions of whales are updated according to Eq. ations (4, 5, 6 and 7). Fig 2 shows how the current solution (whale) W_i, iteratively converge, towards the best solution W^* (the location of the prey), Fig 2 represents the solution in two dimensional space

B. Spiral updating position

(8)

The following steps accomplish the imulation for this behavior:

- a) The distance between the current position. (solution) W_i and the best solution W^* is calculated.
- b) The helix-shaped movement of .he humpback whales is mimicked by creating a spiral equation as follows:

$$\vec{W} t + 1) = \vec{D}' \cdot e^{bl} \cdot \cos(2\pi l) + \vec{W}^*(t)$$
$$\vec{D}' = \left| \vec{W}^*(t) - \vec{W}(t) \right|$$
(9)

Equation 9 represents the ω_i tance between the ith whale (W_i) and (\vec{W}^*) the best solution obtained so far, *l* is a random number in the interval [-1, 1] and b is a constant that defines the logarithmic spiral's shape [43].

According to the previous equations, the humpback whales move towards the prey with two different kinds of move nents simultaneously:

- (1) According to equation (4, 5, 6 and 7), the humpback whales move around the victim within a shrinking circle.
- (2) According to equation (8 and 9), the humpback whales move towards the prey in a spiral-shaped path.

In WOA algorithm, the whale is switching between these two kinds of move here with equal probability as shown in equation 10 [50].

$$\vec{W}(t+1) = \begin{cases} \vec{W}^*(t) - \vec{A}\vec{D} & \text{if } p < 0.5 \\ \vec{D}'.e^{bl}.\cos(2\pi l) + \vec{W}^*(t) & \text{if } p > 0.5 \end{cases}$$
(10)

Where p is a random number in the interval [0,1]

Exploration phase (search for pray)

The humpback whale searches for the prey randomly in the conformation phase adopting a different technique by updating his position according to a randomly chosen candidate instead of the best candidate like in the exploitation phase. Mathematic, $||\cdot|| \le 1$, the candidate whale moves far away from the reference whale performing a glocal search as in equations 11 and 12 [43].

$$\vec{D} = \left| \vec{C} \cdot \overrightarrow{W_{rand}} - \overline{W} \right| \tag{11}$$

$$\vec{W}(t+1) = \vec{V}_{\cdot, \cdot, \cdot, nd} - A \cdot \vec{D}$$
(12)

 $\overline{W_{rand}}$ is a random position for the randomly the sen whale from the current population of whales.

In WOA, the positions of the search agents as updated at each iteration according to the value of $|\vec{A}|$, if $|\vec{A}| > 1$ the position will be updated randomly according to randomly chosen search agent and if $|\vec{A}| < 1$, the position will be updated randomly according to the best solution. So, the parameter (a) is used to switch smoothly between exploration and exploitation phases. Also, the parameter p controls the switching between the tradition of whale's movement "spiral or circular motion [50].



Fig 2. Bubble-net attacking method (exploitation phase) and searching to prey dechanism (exploration phase) implemented in WOA

9

3. Hybrid Real-time Remote Monitoring (HRRM) Architecture

The proposed (HRRM) facilitates delivering health care to the patient's home. It enables smart hospitals to monitor patients outside of conventional hospital settings and thu increases the number of patients covered by care service and reduce the cost. The smart hosr and is a hospital that improves patient care procedures and creates new capabilities by adopting new technologies such as cloud computing, cloud storage, Internet of things (IoT), etc. The proposed architecture is designed over big data model to extract knowledge from gathering a sive amount of medical data, behavioral information and ambient data generated from the contract sous monitoring of a significant number of patients in real-time. As depicted in **Fig 3**. HRK, ⁴ consists of four layers as follows:







3.1. Layer 1: Patient's House Module (PHM)

HRRM manages a large number of PHMs for patients monitored by the smart hospital. Each PHM is responsible for gathering sensor data that includes medical data (physiol/ gical signals), behavioral patterns (smoking, drinking alcoholics, taking medications, etc.), ambient data (humidity, temperature, noise, etc.), contextual information (location, activity, etc.). The right setup of the RPM system guarantees building reliable supervision $s_{j,s}$ m taking into consideration the patient's illness type and his social condition. Each differs type requires selecting suitable actuators, ubiquitous devices, and IoT sensors along with solution are programs to obtain the necessary sensor data to extract knowledge about the health state of the patient in the hybrid architecture. Layer 1 is composed of the following components:

3.1.1 Biomedical IoT Platform

Biomedical sensors are vital instruments in the modern medicine cred to collect sensor data that has information on human body and pathology. The continuous development of biomedical sensors provided the market with precise, sensitive, and fas rec_Ponse sensors with competitive price capable of collecting patient's vital signs in real time. Electronic medical (eMedical) kits integrate different types of sensors into one package or add new sensors for building a new medical device as in MySignals eHealth and medical IoT platform [52]. It facilitates measuring more than 20 biometric parameters such as (position, crygen in the blood, glucose level, blood pressure, pulse, etc.). Furthermore, it supports many connectivity options such as (GPRS, 3G, Bluetooth, Wi-Fi, ZigBee, IEEE 802.15.4, etc.).

3.1.2 Ambient Intelligence devices (AmI)

It refers to electronic environments created u. ... set sors that are sensitive and responsive to the presence of the patient and providing important embient sensor data needed for the study. Ambient sensors are easily embedded ... **PNA** through different communication media to recognize the patient and his situational context. Furthermore, they can be tailored to the patient's needs and exploit its adaptive and anticipative capabilities. The goal of using ambient sensors in the proposed module is to adaptive and anticipative capabilities. The goal of using ambient sensors in the proposed module is to adaptive and entry context awareness to the model. Also, it helps in understanding the effect of ambient conditions on patient's physiological signals. Ambient sensors that can be used including, but not limited to, room temperature sensors, humidity sensor, and smoke det ctor

3.1.3 Data Forwarder (DF)

It forwards the collected low-leve, tensor data from ambient devices and high-level sensor data from the eMedical platform, ver different communication media. DF forwards Low-level sensor data to High-Level Context Provider (HLCP) in Patient Local Module (PLM) converting it to a higher level of abstraction while it forwards high-level data directly to High-Level Context Aggregator (HLCA).

3.2. Layer 2: Pf Jont's LJcal Module (PLM)

PLM is a cen ral loc l module responsible for receiving, processing and aggregating the generated sensor Line in PHM into one context state. Also, it has a smart unit validating

communication with the cloud part of the hybrid model. Furthermore, it acts as a backup module for monitoring the patient by classifying his health status in the case of internet disconnection or when a problem occurres in the cloud system. PLM contains the following components:

3.2.1. High-Level Context Provider (HLCP)

This unit converts raw sensor data to a higher level of abstraction by $adoptir_{\circ}$ nany techniques such as feature selection, fusion algorithms, and classification algorithms the the converted sensor data is forwarded to High-Level context Aggregator (HLCA).

3.2.2. High-Level Context Aggregator (HLCA)

This unit is responsible for the aggregation of the output of differe. * FLCPs and sensor data generated from biomedical IoT development platform in one contract state. Each context state contains sensor data such as vital signs, ambient data, associated a stivity, behavioral information, etc. at specific time slot in the form of high-level values. The mini. α for *p* sembled context states will reveal many mysteries about the fluctuations in patients vital signs. For example, the increase in HR above the normal range during jogging is in error etc. as a normal case, but it is worth investigating if it occurs while the patient is relaxed [5].

3.2.3.Connectivity Validator (CV)

This unit examines the connectivity between the local module and the cloud modules in the proposed hybrid architecture to select the suitable model coordingly. Internet connection is regularly tested with different measures such as network latency, download speed, upload speed, etc. to switch smoothly between the modes of the model. If CV verifies that the connection is valid and stable an online mode would be selected to classify patient's health status on the cloud side of the architecture while if CV detects invite the communication system; offline mode will be chosen to do the same operation on the local part using a backup classification model.

3.2.4.Local Database (LDB)

This unit stores the collected context states reaching to PLM in the offline mode. Also, it contains a backup classification model for classifying patient's health status locally in offline mode when there is a problem in the cloud system. Furthermore, it offers storage space for an updated copy of patient's a sistile services, medication time, prescriptions, precautions, prohibitions, radiological investigations, medical reports, etc. which are available also for the cloud part of the hybrid archemeter.

3.2.5.Personal Medical (ass'stive Service (PMAS)

PMAS is a tailored service for every patient according to his illness type and social status. A medical committee composed of a family member, social researcher, physician-in-charge, caregiver and administrative staff puts suitable assistive services for every patient. Assume that classes, which identify be lent's health status, are as follows (Normal, Warning, Alert, and Emergency). In Normel cases, the system should work without generating any alerts. In warning cases, a warning message will be sent to caregiver and physician-in-duty. In alert cases, caregivers and physician-in-charge will be called to follow the case in addition to one of his



relatives, neighbors or friends. In emergency cases, physician-in-charge and ambulance will be appealed directly to transfer the patient to the hospital. All these notifications can be displayed on monitor or patient's smartphone. Also, a video call can be held between doctor-in-charge and the patient to give him instructions in alert and emergency cases.

3.3. Layer 3: Patient's Cloud Module (PCM)

This module acts as a personal information repository for every patient monitor d by HRRM. It is used to classify patient's health status in online mode. PCM consists of the to 'owing clouds:

3.3.1. Patient's Personal Storage Cloud (PPSC)

PPSC is a personal cloud storage area; every patient who is monitor 1 by the smart hospital has his own PPSC. This repository retains context states aggregated during system's operation in offline mode until uploaded to the Central Knowledge Discover / s Cloud (CKDC). Also, this cloud keeps patient's profile (e.g., name, age, gender, weight, height, illne s history, etc.) and the thresholds of patient's physiological signals, which are taken from M dical Monitoring Cloud (MMC). Furthermore, it keeps medical tests, radiologic 1 in c tigations, medical reports, prescriptions, medicine name, its dose, time, patient's behaviors like smoking and drinking alcoholic beverages, etc. Finally, it retains the last updated version of assistive services approved by the medical committee.

3.3.2. Medical Monitoring Cloud (MMC)

This cloud contains all entities helping in the monik and operation of the patient both inside and outside the smart hospitals. This cloud has a connection to all persons or services' provider assigned to provide help to the patient when his beautified deteriorating. Medical experts transfer their medical knowledge to MEC in the form of geterior medical rules while physician-in-charge is responsible for putting personal medication and move them to PPSC. Furthermore, physician-in-duty monitors the patient remotely and responses to alarms generated in alert and emergency cases by taking immediate action to save his life.

3.3.3.Medical Encyclopaedia Cloud (*****C)

This medical encyclopedia retains all med cal information according to recent researches for every illness type, physiological rignals that must be monitored and their ranges and associated symptoms in the form of generic medical rules. The generic medical rules are used with personal rules in building a personalized chastification model for every patient which will minimize false alarms. MEC is updated with any new discovered generic rule from knowledge discovery process as will explained in tay. 4.

3.4. Layer 4: Hybrid K now edge Discovery Module (HKDM)

HKDM is a hybrid rodu, that contains components on both local and cloud sides used for knowledge extraction and the classification of patient's health status accordingly. The hybrid architecture aims to poloit merits of both local and cloud architectures and avoid their flaws. The cloud part of the nodule facilitates working with big data regarding storage and computations, in the other hand, the local part of the module will solve the weakness of the



cloud-based models in case of internet interruption or a failure in the cloud system under any circumstances. This module consists of the following components:

3.4.1. Central Knowledge Discovery Cloud (CKDC)

CKDC is one of the core components of the proposed framework, which includes many distributed clouds with large storage capacities to accommodate all context strue generated from patient's continuous monitoring. Spark is used to distribute a vast number of corrects, maybe for millions of patients' across different clusters then applying different machine is rning techniques in parallel to speed up the knowledge discovery process. As shown in **Fig. 3**, the knowledge discovery process is done vertically across the four layers by converting the work data into the first layer into high-level data by HLCP, and then aggregate them with contextual and medical information by HLCA into unified contexts states in the second layer. Generic and personal medical rules are used in the third layer to build a dynamic mod 1 cust mized according to the patient's health status. In the fourth layer, machine-learning techniques are used to extract the knowledge about the patient's health status using a massive number of contexts.

3.4.2. Online Classification Model (OCM)

The learning phase in the proposed classification technique convists of five consecutive stages to build an accurate classifier working in online-mode and capal le of dealing with imbalanced datasets. The best-learned model among all clusters will be subjected by voting to predict patient's health status in online mode; this technique aims to maximize the accuracy of the classification and minimize the elapsed time. (Will be presented in detail in section 5).

3.4.3. Offline Personal Classification Model (C "CF 4)

OPCM is a backup copy of OCM that work on the local side (offline mode) when the internet connection interrupted, or failure happens in the local system. According to the result of the classification, one of PMAS services, which are sorted in LDB, will be called to take appropriate action.

3.4.4. Synchronizer and Scheduler 'Jnn (SSU)

This unit is responsible for information exchange between HKDM, PLM and PCM to ensure that each module has the last version of information required for its proper work. The synchronization of offline cont xt s ates stored in LDB with PPSC is performed according to a predefined schedule. Moreover, the instant synchronization of the new version of OCM with OPCM to be used in offline last version on the local side is performed. Furthermore, it ensures that PLM has the last version of r. ⁴AS.

4. A Case Study on ^Pat ents with Blood Pressure disorders

An imbalanced data et is a cutaset that the number of tuples belonging to the majority class outnumbers those 'elor ging to minority classes [53,54]. For example, it is normal in datasets that the patient's healuh of us is classified to one of these classes: (Normal, Warning, Alert, and Emergency) according to patient's context state to be imbalanced. The majority class is a Normal class, while Energence and Alert classes are the minority classes. As, most classifiers are accuracy-driven that any concentrate on maximizing the overall accuracy and minimizing the

overall errors assuming that the distribution of classes is normal and the cost of errors obtained from different classes is same so, they will be biased towards majority classes rather than minority ones [55]. Handling imbalanced class distribution can be classified as following: sampling methods [56,57], cost-sensitive [58,59] and kernel-based methods [60].

A case study is implemented to evaluate the performance of HRRM and . prove its efficiency in classifying patient's health status and its ability to deal with it to 'anced datasets. This case study has the following objectives:

- a. Verifying that HRRM correctly comprehends the health situation of the ration, using contextawareness to achieve more accurate results than traditional systems t¹ + ado_F generic rules in classification.
- b. Verifying that HRRM succeeded in addressing the problem of the n. ^L flanced datasets and its dramatic exacerbation with big data.
- c. Validating that the proposed classification technique (HKDM) su ceeded in building a coherent learning model for big data generated from HRRM using a listributed cloud model to speed up classifications and giving instant, accurate results.
- d. Validating that the proposed bio-inspired algorithm (NE W JA) succeeded in selecting the minimum sets of features required for the operation of the model with the highest efficiency and fastest performance.
- e. Electing the best classification technique and the best samping methods that give the best results and suitable to operate with HRRM.

4.1. Case Study Description

As illustrated in **Table 1**, this study has been conducted on three elderly patients suffering from Blood Pressure (BP) disorders and their details file as follows:

	Patient 1		Patient 2			Patient 3		
Patient record	a414? •	a41466			A40208			
Gender	Femar	Male			Female			
Age	71 y ars	66 years			78 years			
Birth date	27-Aug-1/41		11-Mar-1944		11-Feb-1937			
Illness category	Hypertension		Hypotension		Normal + Transient Elevation in BP			
Monitoring start ate	31-Aug-2012		22-Jun-2010		15-Mar-2015			
Monitoring durates	Γ μy Month ✓ ✓	Year 🗸	Day	Month	Year 🗸	Day ✓	Month 🗸	Year ✓

Table 1. F. the "ts' 1 cords

The HRMM has monitored the patients for varying periods as listed in **Table 1** to evaluate its performance in predicting the health status of these patients.

The measuring of physiological signals four or five times daily is not enor gh to diagnose serious medical illness, especially in medically unstable cases. Thus, the patients were continuously monitored by taking measurements every 15 minutes.

The vital signs vary with the ambient conditions such as humid y, roise, and room temperature. Also, the behaviors of the patient such as smoking, drinking any holic beverages, taking medications, physical activity, and stress are the major factors of us fluctuation in his vital signs. Additionally, many additional factors can explain the variations in the patient's physiological signals including age, the degree of the illness, disea e's factory and the family profile [61,62].

The HRMM has exploited this data to build a context-aw re clas. fication model, which is smart enough to distinguish between the different situations and their effect on the physiological signals of the patient. Also, this framework is capable of comprehending the nuances between the different patients. The consideration of these points in the design of the HRMM leads to building a smart, coherent, accurate, and fast framework. Accordingly, this technique will minimize the false alarms that are usually generated from such AALs especially those systems that depend on general medical rules in its preatic 1 (traditional AALs).

The learning phase has been performed in the C^TKDM) utilizing large historical data from many patients with the same category of illne . The CCM uses the data stored in the KDC to train a classification model for every illness's category. The OCM detects the emergency cases in real time and informs the medical assist. Comm to take the appropriate action.

Datasets will be distributed among different H. toop clusters, and the learning phase will be performed in parallel using ensemble vote's crissification technique to manage the massive data and speed up the classification process to give results in real time. WEKA (Waikato Environment for Knowledge Analysis) will be used to simulate the proposed classification technique OCM using Spark and evaluate it with different classifiers and sampling methods [63,64].

4.2. The clinical dataset

The clinical data of the elderly ratients suffering from blood pressure disorders that are used in these case studies have been taken from PhysioNet MIMIC-II [65].

4.2.1. PhysioBank

The PhysioBank cor⁺ ins four terabytes of digitized vital signs and time series containing over 90,000 recordings orga ized in more than 80 clinical datasets, and classified according to the types of signals incluct d [66]. The clinical databases include continuous measurements for some vital signs along with, laboratory test results, procedures, medications, caregiver notes, images and imaging ver orts, and mortality (both in and out of hospital).

4.2.2. The MIM' II dambase

The MIMI ⁻-II dat base is the extension to the first attempt of building a database called MIMIC that <u>contained</u> ulti-parameter recordings of ICU patients in the period between 1992 and

1999. The MIMIC II Clinical Database was released in 2011 including over 32,000 subjects for more than 40,000 patients who have been admitted to cardiovascular, medical, surgical, surgical recovery units, and coronary care units at the same hospital [67].

As illustrated in **Table 1**, three patients have been selected to represe i the different categories of BP disorders. Moreover, they are used to test the classification m social (OCM and OPCM) of the proposed HRMM. Additionally, the OCM uses the data of a large number of patients including these patients to train the classifiers in the learning phase.

4.3. Synthetic Data Generation

As far as we know, there are no real datasets that similar to the data the vill be collected by the proposed model. The targeted dataset contains physiological signs, a sociated activity, ambient conditions, and behavioral information for patients with blood ressure disorders. The continuous monitoring will extend to a year by taking a sample very 15 minutes as shown in **Table 2**. Therefore, datasets will be synthetically generated based on real patients' physiological signals taken from Physionet MIMIC-II database for three patients on minute data generated from biomedical IoT platform in HRRM [68].

Timestamp	HR	SBP	DBP	MBP	RR	SPO ₂	Temp.	Act.	L. Act.	Med.	Sym.	Class
23-03-16 0:00	78	159	91	106	19	100	0	1	1	1	3	Warning
23-03-16 2:45	102	144	61	111	10	100	υ	2	2	0	17	Alert
23-03-16 3:00	60	146	81	96	18	100	0	\sum	2	0	0	Normal
23-03-16 4:15	86	146	63	103	17	100	2	2	2	0	0	Normal
24-03-16 0:00	62	181	91	104	23	100	1	1	1	0	1	Emergency

 Table 2. A sample of the final dataset

The synthetic dataset takes into consideration the for twing criteria:

- a. The correlation between activities and physical signals according to **Table 3** that shows the percentage of increase in HR according to different events (e.g., HR is average when the patient is watching TV, but it will be higher when he is on the treadmill) [69].
- b. The plausibility of activity time (e.g., eating at 3 p.m. and sleeping at 1 a.m.).
- c. The effect of ambient conditions and uairing medications on physiological signals.

d. The relationship between patien. 's health status and symptoms.

The generation of synthetic datasets is $p_{x} + f_{x}$ rmed using MATLAB for hypertensive, hypotensive, and normotensive patients in a year with the same distribution as in real Physionet MIMIC-II datasets. This technique is reliable in the generation of synthetic datasets that are similar to real datasets, which are verified in previous studies of biomedical data analysis [14,70]. Some abnormal physiological signals are added without modifying the remaining attributes of these context states to represent mergency and alert cases. The possible symptoms for each category (Hypertensive patients, hypertensive patients, hypertensive patients, hypertensive patients, hypertensive patients, hypertensive patients, and Normotensive patients with transient elevation in blood pressure) are predicted in **Table 4**. **Table 5** shows all Types and ranges for all attributes in the generated date sets that are used in the experiment [71]. **Table 6** illustrates the situational classification mode used to distinguish the class according to personalized medical rules. **Table 7** shows a set of ass. tive services that will be executed according to the result of the classification.

Table 3. The percentage of HR increase according to each activity type [69]

Activity	The percentage of HR increase.
Laying	0-10%
Sitting	5-15%
Standing	10-25%
Walking	15-45%
Running/Cycling	35-100%
Stairs	15-80%

Table 4. Symptoms according to patient's category in the experiment.

Туре	Symptoms	alue on y)
Hypertensive	A headache & Anxiety - Fatigue- a severe	t c binary
	headache & Anxiety - Pounding in your chest	(value. ^ to 63)
	neck, or ears - Vision problems and confusior -	
	Chest pain and difficulty in breathing	
Hypotensive	Lack of concentration – Fatigue - Blurred vision -	6-1.t binary
	Dizziness - Rapid shallow breath - Fainting	(value: 0 to 63)
Normotensive	Uncomfortable- Anxiety – a headache – I atigur	6-bit binary
	a severe headache - Dizziness	value: 0 to 63)

Table 5. Types a	nd ranges for	attributes	used in th	ie 6. 1	periment	[71]

Name	Attributes	Туре	Range
			value
Vital Signs	Heart Rate (HR)	Numeric	[30-200]
	Systolic Blood Pressure ()	Numeric	[50-230]
	Diastolic Blood Pressure (DBr,	Numeric	[30-140]
	Respiratory Rate (K)	Numeric	[5-30]
	Oxygen Saturation $(S_1 ^{\circ})$	Numeric	[40-100]
Activity	Current Activ. T ast A tivity	Resting	1
		Sleeping	2
		Walking	3
		Eating	4
		Exercising	5
		Household	6
Ambient conditions	Roc 11 tenip rature	Normal	0
		Hot	1
		Cold	2
Medication	Taken or	Boolean	0 or 1
Symptoms	Sy aptoms	Boolean	[0-63]

 Table Classification according medical model

Class	Classification
Normal	HR, ⁶ 3P, ⁷ 3P, RR, and SPO ₂ all values are in expected Range concerning current activity
	and sy. $\gamma t /ms = 0$
Warning	A y of Hr, SBP, DBP, RR and SPO ₂ increase above the normal range to the warning
	ange f medications not taken or symptoms > 0
Alert	'ny of HP SBP, DBP, RR and SPO2 increase above the warning range to the alert range
	or n. "" f an two vital signs in warning range and (medications not taken or symptoms >
Emergei :y	Any of HR, SBP, DBP, RR and SPO ₂ increase above the alert range to the emergency
	rang or more than two vital signs in alert range and (medications not taken or symptoms >

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Case	Action
Class = Normal	Do nothing
Class = Warning	Warning on patient's mobile or monitor in his home or SN $_{3}$
Class = Alert	SMS or phone call to the \ physician-in-charge to revi 're
	case
Class = Emergency	Call ambulance directly or after confirmation from picn-
	in-charge
Medication = 0	Alert the patient or the care giver

Table 7. Examples for assistive services

4.4. The exploration of the generated datasets

The generated datasets for three patients in a one-year and the distribution of classes are illustrated in **Table 8**, as well as **Fig 4**. It is clear that when general redical rules had been applied to classify the generated contexts to normal and abnormal classes, it failed in classifying most of them, and that, of course, will make the system generates nany false alarms. HRRM uses context awareness to comprehend the real situation of petient's health taking into consideration ambient conditions, behavioral information and associated activity to give results that are more accurate. It is clear that the generated dataset are severely imbalanced and (Emergency) class is the minority class while (Normal & Varring) classes are majority classes. Therefore, different sampling methods will be applied to the sed datasets to address the problem of imbalanced datasets in addition to classification techniques using WEKA and Spark [64,72].

Table 8. Comparison between classifications with HRN 2 comparison traditional AALs for three patients in a year

Patient	No. of contexts	Tradit nal Ar.		HRMM			
		Normal	A. orm.d	Normal	Warning	Alert	Emergency
P1 (Hypertensive)	35232	2	\$230	9307	23347	2404	174
P2 (Hypotensive)	35232	3	55229	19455	14003	1627	147
P3 (Normotensive)	35232	1	35231	12517	21421	1186	108



Fig 4. The distribution of classes for three patients' datasets over one year using the HRMM

4.5. The implementation of the case study using Weka and Spark

Table 9 shows hardware specifications of PC used in all experiments, operating system, programming software, and its plugins. The Distributed Weka Base package *e* id Distributed Weka Spark package must be installed after installing the last version of WE¹ A as shown in Table 8 [73].

Name	Detailed Settings	Name	Detailed Settings
Hardware		Software	
CPU	Intel ® Core TM I5 3317U	Operating System	Windows 10 6 bit
Frequency	1.7 GHz	Software	MATLAB R2 16b (.1) 64 bit
RAM	6 GB		WEKA 3.8.1
			Plugins:
			Distribu dWekaB. e version (1.0.17)
			Distribut dWekaSpe k version (1.0.9)
Hard Drive	1 TB		SM / IE version (1.0.3)

Table 9.	Hardware	and	software	specification	s
				1	

5. The Proposed Hybrid Knowledge Discovery Lode! (AKDM)

The proposed Hybrid Knowledge Discovery Model ($H^{\vee}DM$) consists of two classifiers, one of them called Online Classification Model (OCM) that vorks vorks vorke cloud side (online mode). The other one called Offline Personal Classification Model (Or $\mathbb{C}M$) which is a backup copy of OCM that works on the local side (offline mode). The isotrong phase of the proposed classification process is composed of five stages as depicted in **Fig** 5.



Fig 5. T r proposed technique for learning and evaluating CCM

5.1. Online Classificatie . \ \ \ (odel (OCM):

Stage 1: Dataset Prevar. ' on (Splitting data)

As WEKA and Space will be used to implement phases of the proposed classification technique that will be used to construct on the single contexts, it is important at this stage to prepare datasets to work correctly, with them. While '*.arff*' is the default dataset's file extension but to use it with Space it should split into two files using '*arff header Spark job*,' the first one contains the header section of the dataset with extension '*.names*.' and the second one contains dataset



itself with extension '.CSV' (Comma Separated Value). The level of parallelism that will be applied to the dataset is configured in this job by indicating the number of data chunks that will run in parallel on Hadoop Distributed File System (HDFS) or YARN cluster. Also, the same job can be simulated using cores of PC's processor by setting 'master host = local { o of cores}.' In this experiment, datasets will be sliced into four partitions and will be processed using the five cores of the Processor in parallel [63].

Stage 2: Randomly Shuffle dataset

In this stage, "*Randomly Shuffle Data Spark Job*" is used to specify the nut ber of data chunks and the number of instances in each chunk. Furthermore, data chunks r is pratified to ensure that each class has almost the same distribution of class values as the original lataset, which helps in getting the best result, especially when using ensemble-voting classifies. If the minority class has samples, less than the number data chunks, these samples will be conied to each data chunk to make sure that each class is represented in every data chunk at least by in esample.

Stage 3: Data Pre-Processing

It is clear that our datasets are suffering from severe imba'ance as il' astrated in **Table 8**, as well as in **Fig 4**. In this stage, well-known sampling methods such $\$ Class Balancer (CB), Synthetic Minority over Sampling (SMOTE), Random under Sam, ling (R¹ S) and Random over Sampling (ROS) are used to process imbalanced datasets. Experiment, will be conducted using six well-known classifiers from different classification families over the three patients' datasets with and without these sampling methods.

Stage 4: Learning phase

In this stage, each adopted classifier will be first to build four models, a model for every data chunk on a different cluster and this process. In the repeated four more times, using the four sampling methods. The map part of "W is Cussifier Spark job" is configured to train the following classifiers: Naïve Bayes (NB), Declaion tree C 4.5 (J48), Random Forest (RF), Ripper (JRip), Support Vector Machine (SVM). Nearest Neighbour (IBK) on each data chunk. Then, the reduce job will select the best-genere ed machine by a voted ensemble classifier.

Stage 5: Evaluation Phase

In this stage, the evaluation is erfermer for every classifier using ten folds cross-validation by configuring "Weka Classifier Eventuation Spark Job" to do that. This evaluation module is aggregatable so the overall classification process will be performed through two passes; the first pass makes the classifier transing's task is to learn an aggregated classifier over the data and the second pass for evaluation.

5.2. Offline Persona' Clas. 'fication Model (OPCM)

After the evaluation procless is completed for all classifiers, the best classification model (OCM) along with the best saling method will be copied and transferred to the local part of HKDM. This model is cliented CPCM; it will be used for classifying the incoming contexts into the local side (offline mode).



6. The proposed NB-WOA algorithm for improving HRRM

The failure of any Sensor may affect model's work continuity and its performance. When a sensor stops working, the aggregated context state by HLCA will be incomplete so the dataset will have missing values and thus affects the classification accuracy. This p_{+1} or proposes a version of Naïve Bayes classifier called NB-WOA, which is used for features' selection. This version adopts a bio-inspired algorithm called Whale Optimization Alcon hm (WOA) to optimize its performance as shown in **Fig 6**. This algorithm struggles to fit 4 the minimal set of features achieving the best accuracy. The NB-WOA is working in the local portion of the HRMM to achieve the IoT-Cloud convergence by transferring the selection of the features that accelerate classification to the edge of the local portion of the HRM'A. The NB-WOA has the following advantages:

- It simplifies the generated model for better interpretation by the aomain experts.
- It allows the proposed HRRM model to work in the case of sc ne sens rs' failure that doesn't affect the classification accuracy. This classifier works as system.'a protection module, which determines when the system should stop and when shou'd ke provorking in the case of any sensor's failure.
- It avoids the curse of dimensionality.
- It reduces overfitting.

The detailed explanation of NB-WOA is as follows:



Fig 6. Block diagram of the proposed NB-WOA algorithm

²²

6.1. Parameters' initialization

In the beginning, the parameters of WOA (A, C, a, p, l) were initialized. In the proposed model, the WOA provides the naïve Bayes classifier with some whales, each whale repr sents a subset of features from the original dataset in (binary form), "1" means that the features is selected and "0" means not selected. Thus, WOA search to find the best set of features that a bieves the highest accuracy with NB. The whales' positions are initialized randomly.

6.2. Fitness evaluation

The optimization operation needed to apply fitness function to assess every where position is as given by equation 13.

$$Fitness (F) = \alpha \gamma_R(D) + \beta (|C - R|/|C|)$$
(13)

Where $\gamma_R(D)$ is the classification performance of condition feature set P with respect to choice D, R is the length of selected feature subset, C is the aggregate 1 umber of features, α and β are two random parameters that depend on each other, $\alpha \in [0, 1]$ and $p^{-1} = \alpha$, these parameters are related to the significance of the subset length and the clas if $c_{1,0}$ performance. This fitness function is used to maximize the classification accuracy; $r_R(D)$ and the proportion of the unselected features to the aggregate number of features; as in the term |C - R|/|C| [74].

6.3. Termination criteria

When the termination criteria are satisfied, the operation, ends; otherwise, we proceed with the next generation operation. In the proposed model the WCA is terminated when a maximum number of iterations are reached or when the best solution (best set of features (BestF) that achieve the highest accuracy (BestAccuracy)) is the modified for a given number of iterations.

6.4. Updating positions

The positions of whales are then updated as in the in the matical model of WOA in section 2.3.2.

6.5. Algorithm NB-WOA

Input:

- Initialize the whale's population ζ by a ι 'nary code; each whale is composed of a string of feature selection bit.
- Initialize parameters (A, C, c b, 1 and r)
- Initialize BestAccuracy

Output:

• BestF according to Bes. Accuracy

Algorithm:

- 1 while (t < maxim im nui, ber of iterations)
- 2 for each se irch agent
- 3 Update a A, c, 1 and p

4 **If** (3 < 0.5)

```
5
```

/*Shrinking Encircling Mechanism*/ /*Exploitation Phase*/

6	The position of the current search agent is updated by Equations (4, 5, 6, 7)
7	<i>else if</i> (A >1) /*Exploration Phase*/
8	Select a random search agent (X_{rand})
9	The position of the current search agent is updated by Equations (3, 11, 12)
10	end if
11	else if $(p > 0.5)$ /*Spiral Machanism*/
12	Update the position of the current search by the Equation (8. \mathcal{I})
13	end if
14	end for
15	Check if any search agent goes beyond the search space and am' it
16	Remove attributes, which are not selected from the training sa uple and bute to
	get the training dataset T^{\prime} , according to the feature of each whan selection bit.
17	Calculate prior probability P (Ci) of each class of training ata.
18	Calculate likelihood $P(x Ci)$.
19	Calculate the formula = likelihood * prior probability $P(x C^{*})^{* r}(Ci)$
20	Select the maximum prior probability $P(x/Ci) * P(Ci)$ as the predicted class
21	Calculate the fitness function (maximization problem, $\gamma f e \alpha \lambda$, search from equation 13.
22	Accuracy = f with corresponding feature selection BestF.
23	If Accuracy >= BestAccuracy
24	Set BestAccuracy = Accuracy with corresponding feature selection BestF
25	endif
26	Update X* if there is a better solution
27	t=t+1
28	end while

29 Return X*

7. Results and Discussion

Experiments are held to test the proposed HRRIV, with different six classifiers and four sampling methods. The performance of all classifiers with and without different sampling methods are evaluated regarding Accuracy, ov call F-r easure, F-measure for emergency class and time elapsed in each experiment. The priority in the selection of the best classifier along with the best sampling method is in following the order: F-measure (emergency class), overall F-measure, accuracy and elapsed time. Railbing ensures selecting the best combination of classifier and sampling methods for HRRV that works with high efficiency and generate minimal false alarms. Accuracy and F-Measures are colculated from equations 14, 15, 16 and 17 [73,75]. Where, TP = True Positives, FP = False Positives, TN = True Negatives and FN = False Negatives

$$Curacy = TP + TN/TP + TN + FP + FN$$
(14)

$$Recall = TP/(TP + FN)$$
(15)

$$Precision = TP/(TP + FP)$$
(16)

$$Measure = 2 * (Precision . Recall/Precision + Recall)$$
(17)

Table 10 shows the performance of six classifiers with/without sampling methods for a year using OCM that proposed in section 5.1. The best performance among all versions of the classifier (with/without sampling) is highlighted, and the winning algorithm in each data set is highlighted inside a bold square.

Fig 7, **8** and **9** illustrate a comparison between six classifiers regarding accuracy for the data sets P1, P2, P3, respectively. As shown in **Table 11**, the average rank for these classifiers over datasets indicates that J48, RF, and JRip respectively are the best clasafiers that can work with the highest percentage of success in HRRM while the worst are SVM and 10 BK. It is evident that the elapsed time with SVM classifier increases dramatically with big our sets.

Decision tree and rule-based classifiers have the advantage of $g \dots$ rating comprehendible models that can be written in the form of "IF- Then" rules as shown in **F**.g \therefore . This advantage enables the medical team to investigate the generated model to approve or to update general or personal medical rules and relearn the classification model again.

Classifier	P1 (Hypertensive Patient)			ient)	P2 (Hypotensive Passatt)				P3 (Normal Patient)			
	Acc.	F-	F-measure	T.	Acc.	F-	F-measu, T.		Acc.	F-	F-measure	T.
	00.0	measure	(Emergency)	(Sec)		measure	(Emergency)	(ec)	00.0	Measure.	(Emergency)	(Sec)
JRıp	99.9	1	1	10	99.9	I	1	<u> </u>	99.9	0.99	0.96	18
JRip +CB	99.9	1	1	10	99.9	1		J	99.7	0.99	0.85	10
JRip +RUS	99.9	0.99	1	8	99.9	1	1	9	99.1	0.99	0.7	9
JRip +ROS	99.9	1	1	17	99.9	1	1	19	99.9	0.99	0.92	39
JRip +SMOTE	99.9	1	1	10	99.9	1	·	12	99.9	0.99	0.92	23
NB	92.6	0.93	0.92	7	91.1	0.01	0.97	6	96.4	0.96	0.74	8
NB +CB	92.1	0.92	0.98	7	90.7	0.5	_	7	90.8	0.92	0.28	7
NB +RUS	92	0.92	0.98	7	90.7	0.91	1	7	90.6	0.92	0.27	7
NB +ROS	92.1	0.92	0.97	7	90.7	<u>1</u>	1	7	90.7	0.92	0.28	8
NB +SMOTE	91.5	0.92	0.96	7	91.8	1.92	1	7	95.9	0.96	0.68	11
SVM	84.3	0.84	0.79	38	<u> </u>	0.8c	0.26	70	91	0.91	0.65	55
SVM +CB	80.5	0.82	0.97	34	85	0.85	0.6	34	83.2	0.84	0.44	34
SVM +RUS	76.9	0.78	0.98	11	81.5	0.1	0.62	16	81.4	0.82	0.4	16
SVM +ROS	82.9	0.84	0.98	88	88	0.88	0.79	169	84.6	0.86	0.49	174
SVM +SMOTE	84.4	0.84	0.94	5	86 5	0.86	0.71	68	91.1	0.91	0.73	51
J48	99.9	1	0.98	10	99.9	1	0.99	20	99.9	0.99	0.95	8
J48 +CB	99.9	1	1	8	- nr .9	1	0.99	8	99.8	0.99	0.9	8
J48 +RUS	99.8	0.99	1		99.9	1	1	8	99.2	0.99	0.76	8
J48 +ROS	99.9	1	1	9	99.9	1	1	10	99.9	0.99	0.93	10
J48 +SMOTE	99.9	1	0.9	0	99.9	1	1	9	99.9	1	0.95	13
RF	99.9	0.99	<u> </u>	16	99.9	1	0.99	18	99.9	0.99	0.90	18
RF +CB	99.9	1	1	12	99.9	1	1	12	99.7	0.99	0.98	12
RF +RUS	99.9	0.99	1	9	99.9	1	1	10	99.3	0.99	0.75	11
RF +ROS	99.9	1	1	20	99.9	1	1	21	99.8	0.99	0.97	23
RF +SMOTE	99.9	1	1	15	99.9	1	0.99	21	99.9	0.99	0.94	22
IBK	94.3	1.94	0.78	48	93.2	0.93	0.52	44	92.9	0.93	0.72	47
IBK +CB	94.2	<u> 194</u>	0. ^r +	47	95.4	0.95	0.58	47	91.3	0.91	0.74	47
IBK +RUS	81.3	0.82	.85	28	86.2	0.86	0.57	27	82.8	0.83	0.74	33
IBK +ROS	8º J	0.9	0.84	93	91.7	0.92	0.57	92	89	0.89	0.75	107
IBK +SMOTE	9.5	0.95	0.85	47	92.9	0.93	0.64	43	92.8	0.93	0.79	50

Table 10. Comparison between classifiers with/without sampling echniques for patients in one year

Table 11. Classifiers Ranking

Rank	Classifier
1	Decision tree (J48)
2	Random Forest (RF)
3	Ripper (JRip)
4	Naïve Bayes (NB)
5	Nearest Neighbour (IBK)
6	Support Vector Machine (SVM)

As shown in **Table 12**, the best sampling techniques are CB and SMNTE while the worst is RUS. These results proved the ability of HRRM in classifying patients - ealth status with high precision in real-time and recommend using rule-based classifiers (ℓ g., 'Aip) or decision trees classifiers (J48) along with SMOTE or CB as sampling methods for the mobalanced dataset.

Table	12.	Sampling	methods	ranking
				(

Rank	Sampling Tech.
1	СВ
2	SMOTE
3	ROS
4	RUS



Fig 7. Classifiers Ac. aracy v. th/without sampling methods for P1 Hypertensive Patient in one year



Fig 8. Classifiers Accuracy with/without sampling methods 10. "2 Hyr tensive Patient in one year



Fig 9. Classifiers Accur cy with/without sampling methods for P3 Normotensive Patient in one year



Fig 10. The sample for one of the generated model using JR1 classifier

As illustrated in **Table 13** and **Fig 11**, the proposed algorithm NB-WOA is tested over the same datasets of the three patients to select the minimal reatures that achieve the highest accuracy. It needed almost half of the features of the origined datasets to achieve the same accuracy or slightly better. Thus, the size of the dataset will shrink by half, speeding up the classification process. As listed in **Table 14**, the next star is to use these features training and evaluating classifiers and to compare the performance of same classifiers over the original datasets that are listed in **Table 10**. The NB-WC Λ can be used as a safe-fail module to detect when to stop working the model. As listed in the list of the dataset of the hypertensive patient (P1), the model continues its work if the caper that registers the room temperature fails. On the contrary, the NB-WOA will stop the model and and alerts to the stakeholders of the model if the sensors that record the HR and BP fe i. As A substrated in **Table 14**, as well as, **Figs 12 and 13**, the NB-WOA speeds up classifications and preference are accuracy.

Datase	No. of tot .1 featur	Selected features by NB-WOA
t		
P1	11	Five features
		HR, SBP, DBP, RR, and symptoms
P2	.1	Six features
		HR, SBP, DBP, RR, SPO ₂ and symptoms
P3	1.	Six features
		HR, SBP, DBP, RR, SPO ₂ and symptoms

Table 13. The selected feat rest y NP WOA from each dataset to achieve the highest accuracy



Fig 11. Comparison between number of features in the original datase. and he number of features selected by NB-WOA to achieve the same a puracy

	P	1 (Hype	rtensive)	P2 (1. 100. ive)				P3 (Normotensive)			
er	Without NB-WOA		With NB-WOA		Witlert NB-WO.		With NB-WOA		Without NB-WOA		With NB-WOA	
classifi	Accuracy	Time	Accuracy	Time	Accu acy	Time	Accuracy	Time	Accuracy	Time	Accuracy	Time
JRip	99.9	10	99.8	4	¢ 3 .9	14	99.9	9	99.9	18	99.9	9
NB	92.6	7	92.	5	91.1	6	91.4	4	96.4	8	96.8	5
SVM	84.3	38	•	28	86.4	70	86.4	48	91	55	92.1	37
J48	99.9	10	ng	7	99.9	20	99.9	13	99.9	8	99.9	6
RF	99.9	16	,9.9	8	99.9	18	99.9	8	99.9	18	99.9	10
IBK	94.3	48	n5 j	26	93.2	44	93.7	27	92.9	47	93.3	24

Table 14. Com	parison between	classifiers'	peric	mance using	NB-WOA	and without
14010 1 11 0011	parison occureen	•1000111010	Perro	and abing	1.2	and minour



Fig 12. Comparison between the accuracy of the classifers using N-WOA and without



Fig 13. Comparison b tween the Japsed time in classifications using NB-WOA and without

8. Conclusions and Future work

This Paper progresses a Hybrid Real-time Remote Monitoring (HRRM) framework that monitors the elderly patients suffering from chronic diseases in real time. The proposed framework has address d the disadvantages of the local and cloud AAL architecture and exploited the advanted so of both fusing them into a hybrid architecture that has components in both local and cloud environments. The HRRM has transferred the processing of raw data and the aggregatio of high-level data into unified context states to the local portion of the framework instead of clouds as in all cloud-based ALLs. This technique has achieved

convergence between IoT and the cloud portion of the framework through the Patient Local Module (PLM). The HRMM has been examined through case studies on patients suffering from different categories of Blood Pressure (BP) disorders. Experimental results have proved that HRMM is a smart healthcare monitoring framework, which is capable of predict¹ ig the category of the patient's health status from the current context states accurately. The proposed OCM has succeeded in addressing the problem of big imbalanced datasets by processing data chunks using different sampling methods on different Hadoop clusters using Spark. The f ndir as of this study indicate that the proposed OCM has succeeded in increasing the accuracy of of assifications and minimizing error rates, especially for the minority class (emergency class). The OCM has used different sampling methods to preprocess different data chunks acros , 'iffere. t clusters using Spark in parallel to achieve these results. Our research emphasizes t is in postance of the PLM not only for the convergence between IoT sensors and clouds but als, for the preservation of patients' lives in the case of internet interruption or cloud ausconnection. Additionally, experimental results have proved the effectiveness of NB-W DA in electing the minimal features' set that are mandatory to the proper work of the HRMM v. thor. any deterioration in its accuracy. The NB-WOA saves the storage space and accelerate the classifications. Also, it works as a smart safe-failure module that decides to continu. " ... op ration of the framework in the case of non-influential sensor failure. If an influential anso: fails, it stops the operation of HRMM to avoid getting wrong classifications' result that put the patient's life at risk. The directions of the future work include the usage of HRM., in monitoring different illnesses, the observation of context domains that may affect patients vital signs, and the adoption of different bio-inspired algorithms instead of WOA. Additionally the IRRM framework should be tested from the networking perspective.

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Highlights

- A Hybrid Real-time Remote Monitoring (HRRM) framework for ration, suffering from chronic diseases is proposed.
- A Hybrid Knowledge Discovery Module (HKDM) is proposed o c'_ssif patient's health status on dual-mode (online offline).
- The proposed HKDM addresses the problem of imbalanced datasets in big data.
- Naïve Bayes Whale Optimization Algorithm (NB-WOA) is proposed to select the minimum features' set required to ensure the continuity of the model's work with highest efficiency and speed.